

# The 100-year flood seems to be changing. Can we really tell?

Robert L. Ceres Jr.,

**Chris E. Forest**, and Klaus Keller



PennState



SCRiM





# Designing Risk Management solutions are Complicated by:

- Long lifespans
- High cost
- Non-stationary risk
  - Demographics
  - Sea level
  - Weather

# Approaches to Risk Mitigation

## Traditional

- Estimate risk
- Design to a Standard
- Add Margin
- Build
- Hope for the best

## Adaptive

- Estimate risk
- Design to a Standard
- Build
- Look for Signposts
- Reassess
- Implement Planned Response

- We need “signposts,” but...  
will we see them in time?

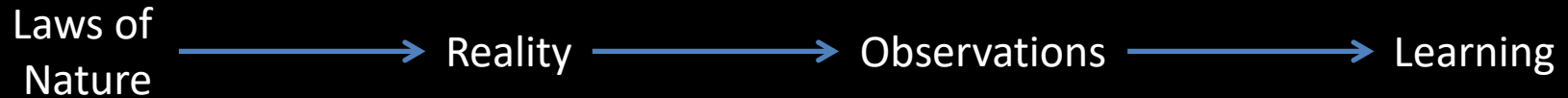
Our main question:

If we prescribe an increasing risk scenario, when can we detect the changes in 100-yr storm surge?

Ceres, R.L., Forest, C.E. & Keller, K. Climatic Change (2017)

# Observation System Simulation Experiment (OSSE)

## Real World:



## Model World:



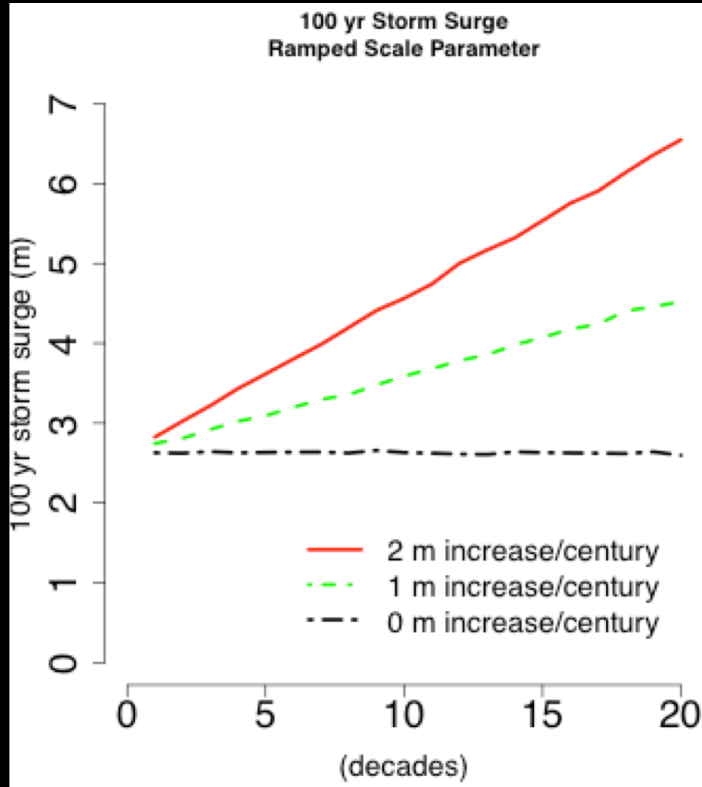
# Experimental Design

- “Laws of Nature” (OSSE “Nature States”) are a GEV distributions with changing (non-stationary) parameters over time.
- “Reality” (OSSE “Nature Runs”) are simulated peak surge levels drawn from the Nature State.
- Observations are estimated 100-year surge levels use Generalized Extreme Value Analysis.

$$f(x; \mu, \sigma, \xi) = \frac{1}{\sigma} \left[ 1 + \xi \left( \frac{x - \mu}{\sigma} \right) \right]^{\left( \frac{-1}{\xi} \right)^{-1}} \exp \left\{ - \left[ 1 + \xi \left( \frac{x - \mu}{\sigma} \right) \right]^{\frac{-1}{\xi}} \right\}$$

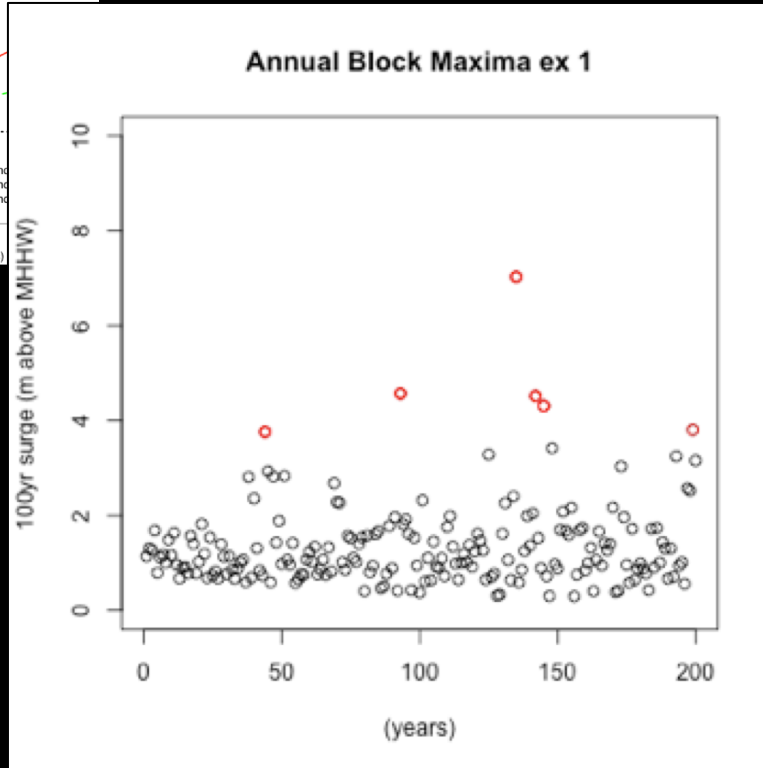
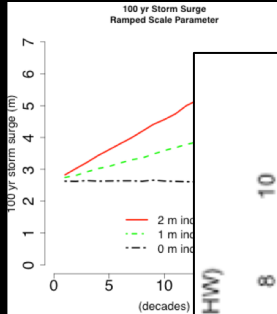
- E1-E4 Nature States with increasing 100-year flood
- 100k Nature Runs per Nature State
- 4 detection models
  - a)  $\sigma = \sigma_0, \mu = \mu_0, \xi = \xi_0$
  - b)  $\sigma(t) = \sigma_0 + \alpha t, \mu = \mu_0, \xi = \xi_0$
  - c)  $\mu(t) = \mu_0 + t\beta, \sigma = \sigma_0, \xi = \xi_0$
  - d)  $\sigma(t) = \sigma_0 + \alpha t, \mu(t) = \mu_0 + t\beta, \xi = \xi_0$



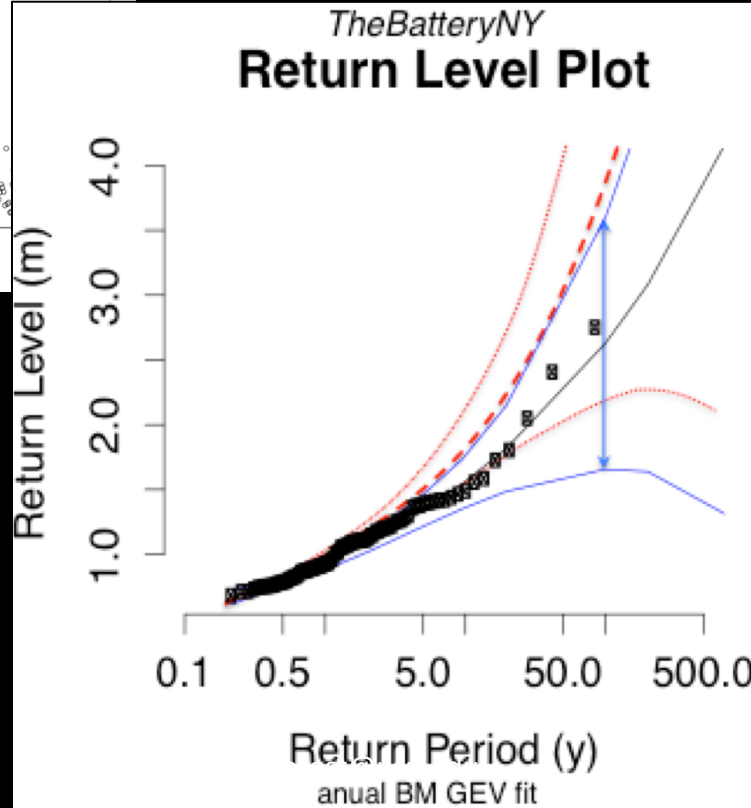
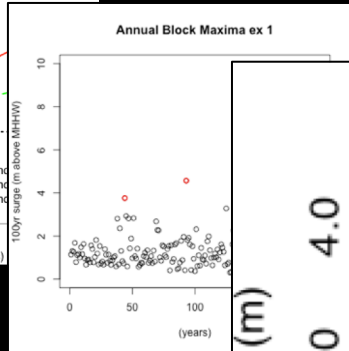
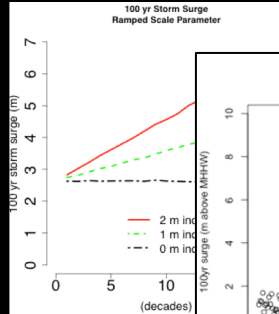


Prescribed an increasing  
100-yr Storm Surge by  
varying the GEV parameters  
to define “Nature States”

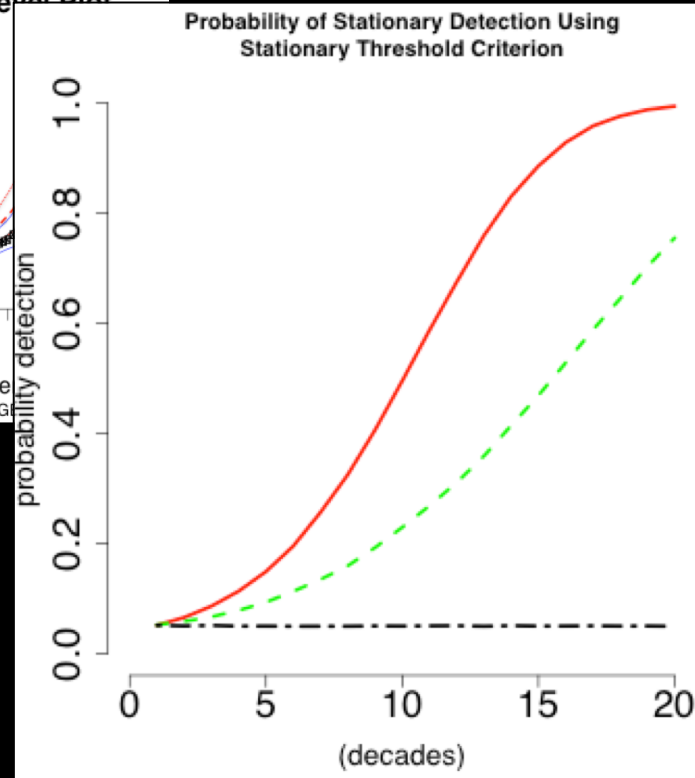
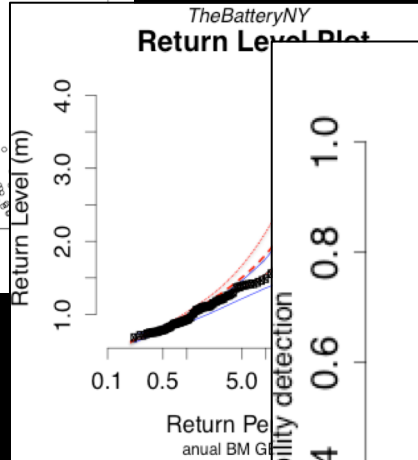
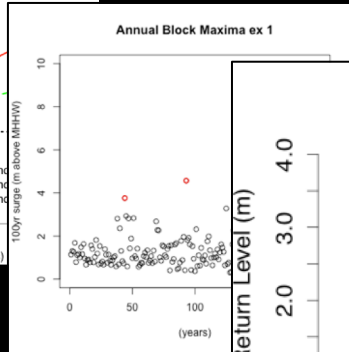
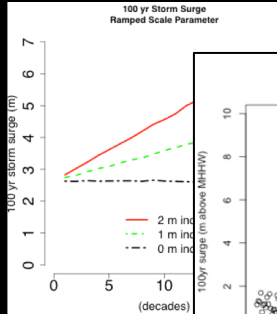
# Generate a single Storm Surge time series from a known “Nature State”



For each new “observation”, we estimate the 100-yr Storm Surge and check for detection for a given record length



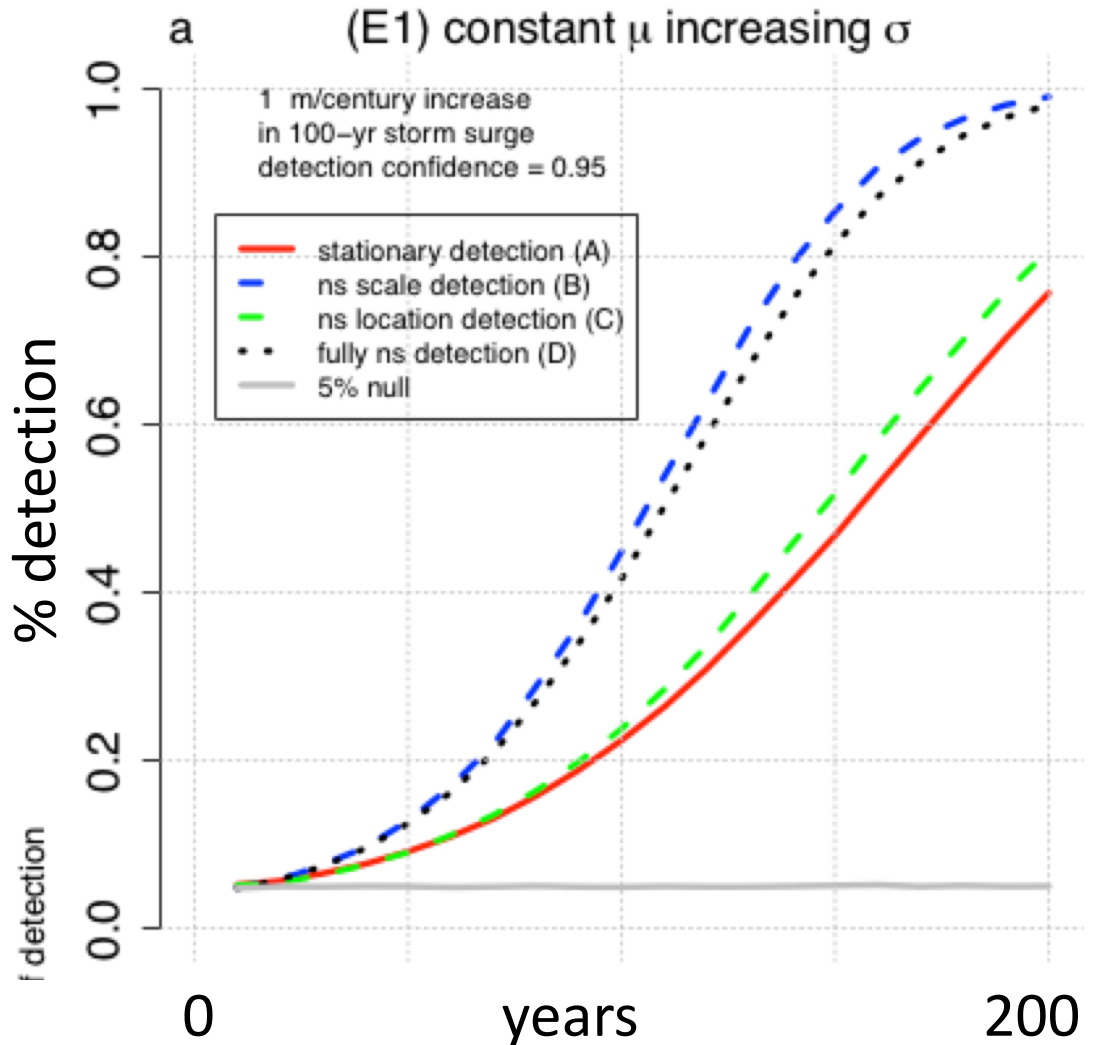
# Generate detection statistics for each length of observing record



# The Detection Model matters for success estimates

1 m/century increase  
in 100-yr storm surge  
detection confidence = 0.95

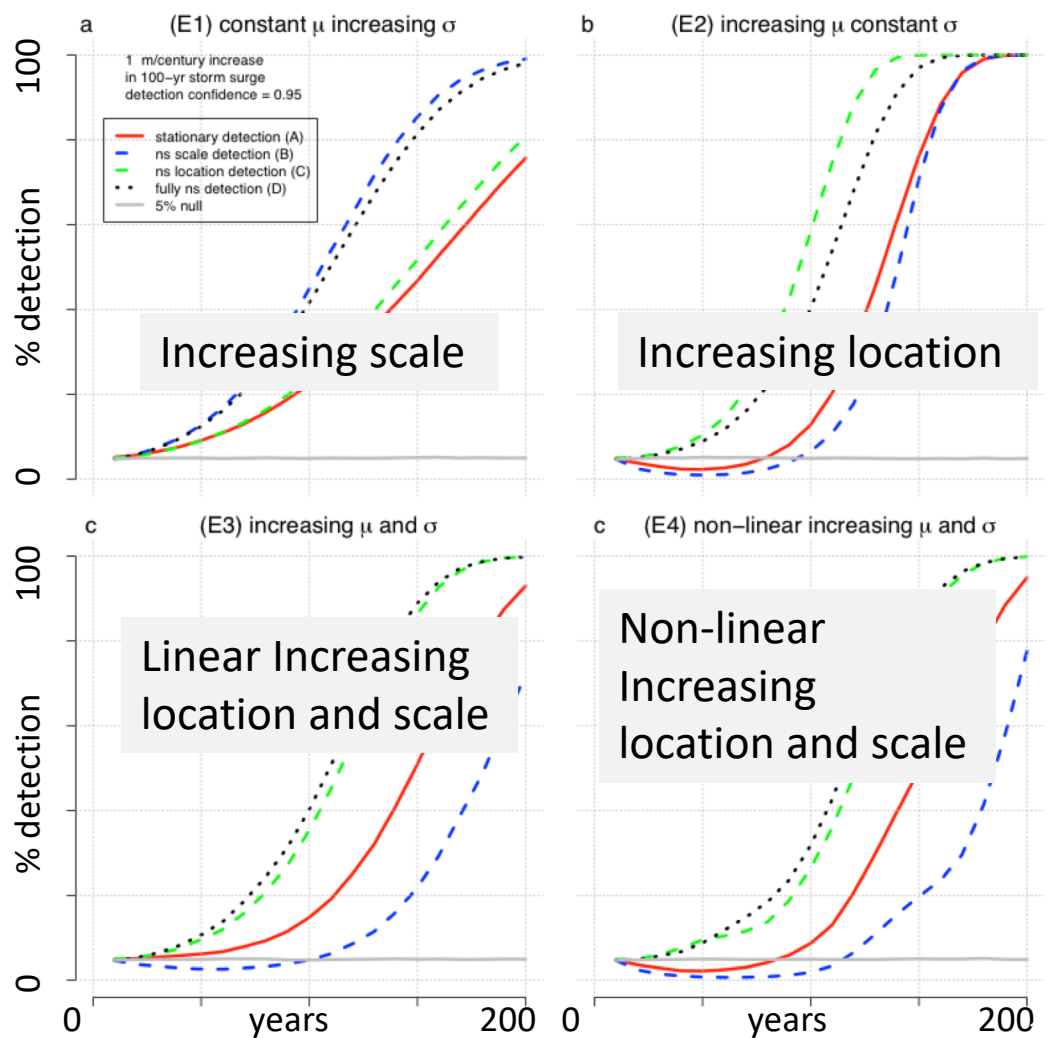
- stationary detection (A)
- ns scale detection (B)
- ns location detection (C)
- fully ns detection (D)
- 5% null



# The Detection Model matters for success estimates

1 m/century increase  
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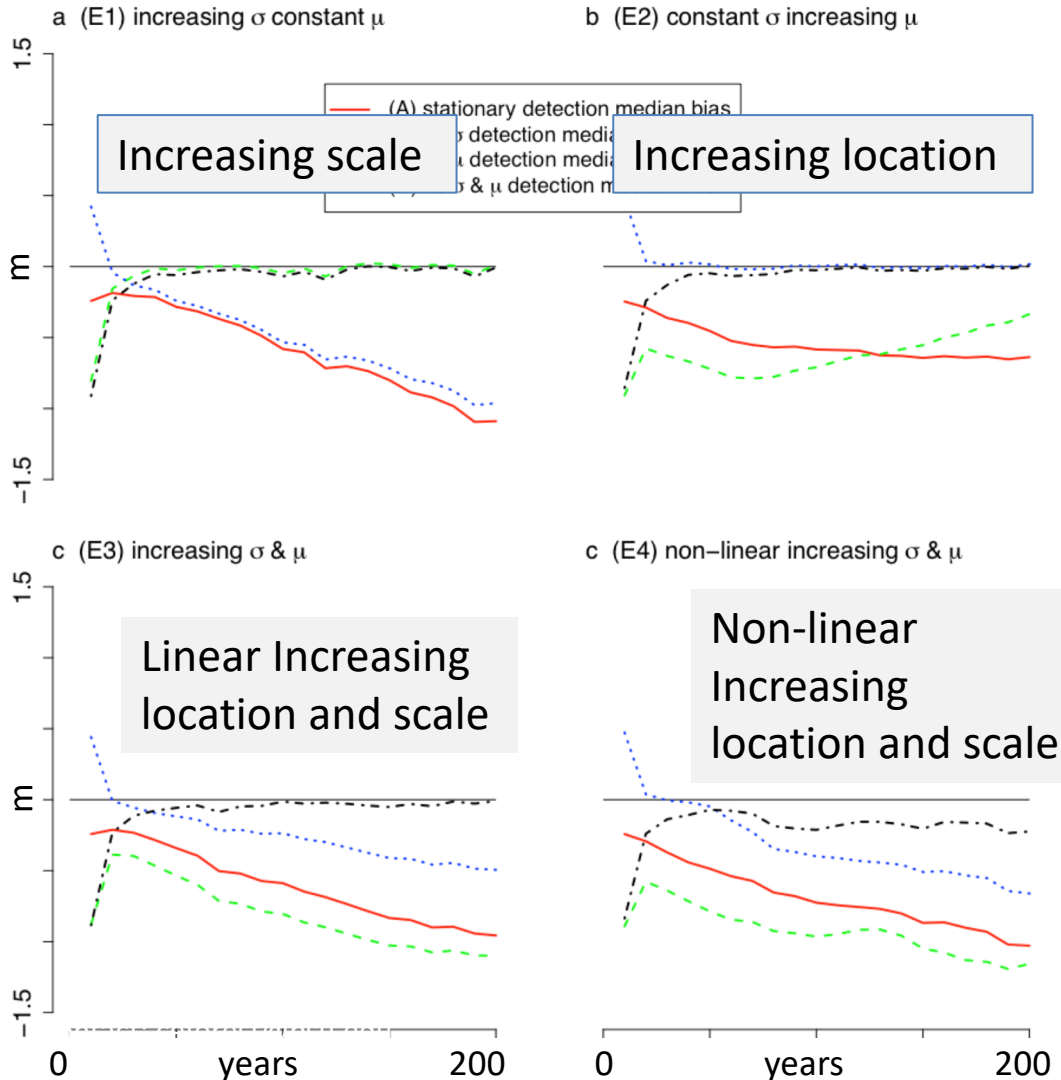
- stationary detection (A)
- - ns scale detection (B)
- - ns location detection (C)
- · fully ns detection (D)
- 5% null



Do we estimate biases in detected median values?

Yes.

- (A) stationary detection median bias
- - - (B) ns  $\sigma$  detection median bias
- · · (C) ns  $\mu$  detection median bias
- · - · (D) ns  $\sigma$  &  $\mu$  detection median bias



# Conclusions

- We can detect changes to the hundred year storm surge, but...
- mismatch between the Nature State and the observation model biases our estimates, which,
- Introduces additional uncertainty that is usually not considered.



- Ceres, R.L., Forest, C.E. & Keller, K. Climatic Change (2017) 145: 221. <https://doi.org/10.1007/s10584-017-2075-0>
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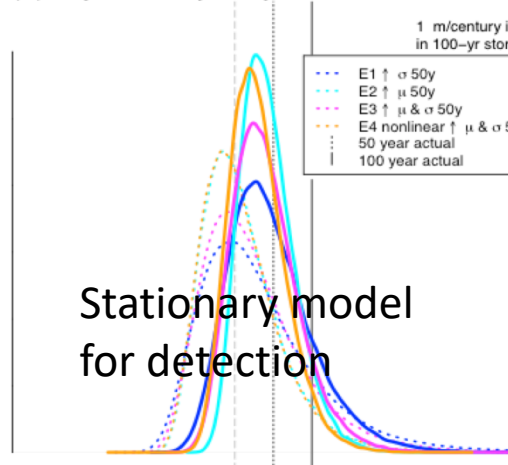
**PennState**



And...

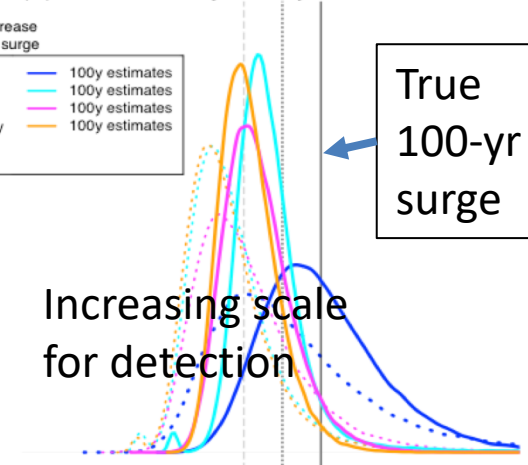
We also estimate biases in detected values.

(A) fully stationary analysis



Stationary model for detection

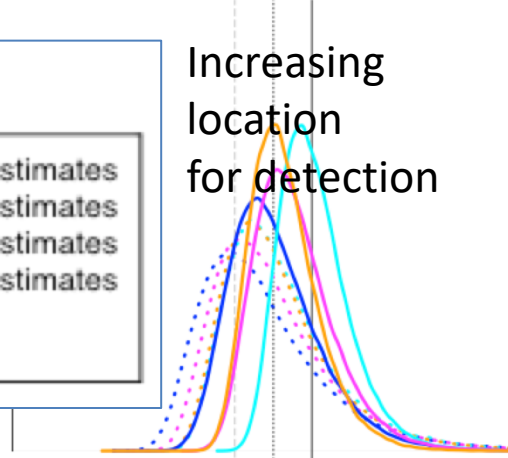
(B) non-stationary  $\sigma$  analysis



True 100-yr surge

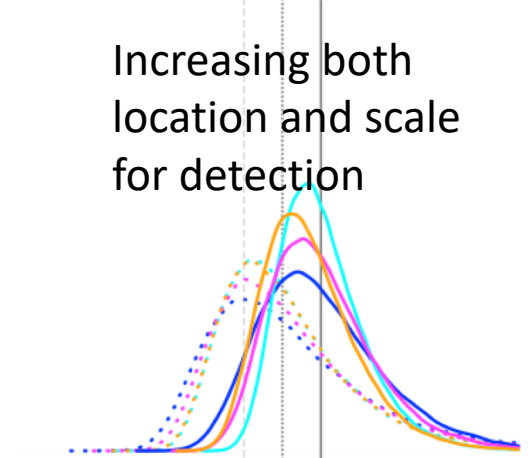
Increasing scale for detection

(C) non-stationary  $\mu$  analysis



Increasing location for detection

(D) non-stationary  $\mu$  and  $\sigma$  analysis

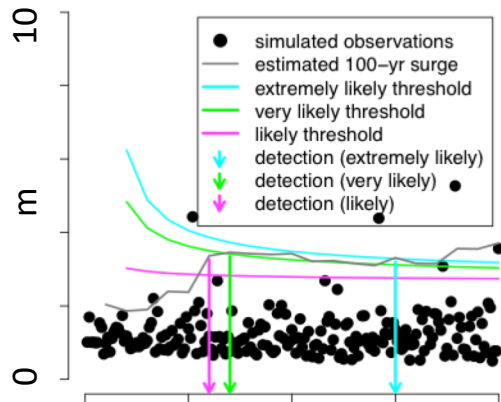


Increasing both location and scale for detection

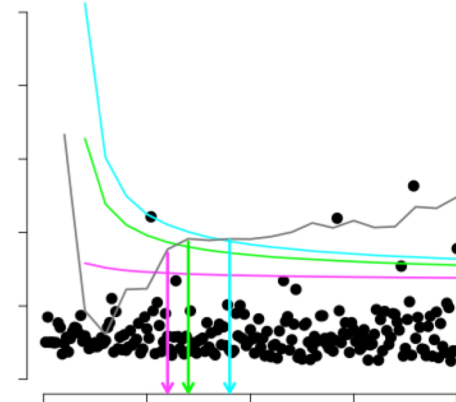
1 m/century increase in 100-yr storm surge

---	E1 $\uparrow$ $\sigma$ 50y	—	100y estimates
---	E2 $\uparrow$ $\mu$ 50y	—	100y estimates
---	E3 $\uparrow$ $\mu$ & $\sigma$ 50y	—	100y estimates
---	E4 nonlinear $\uparrow$ $\mu$ & $\sigma$ 50y	—	100y estimates
...	50 year actual		
	100 year actual		

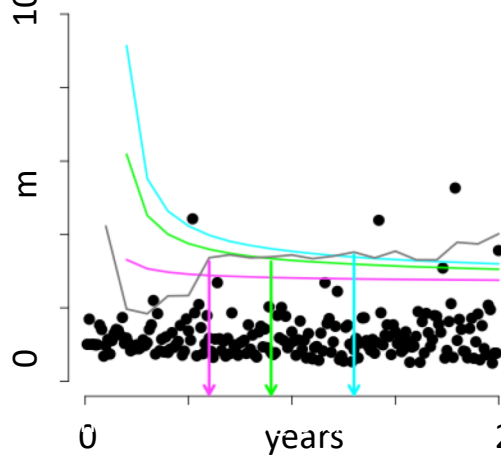
a (detection method A)



b (detection method B)



c (detection method C)



d (detection method D)

