Building a Long-Term Cloud Record from Spaceborne Lidars: Bridging CALIOP to ATLID

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21/05/2025, GEWEX UTCC-PROES, Paris, France

Motivation - how long will it take to detect a trend in clouds using lidars?



Continuous cloud record from space-borne lidars



• General principle is the same: polar orbit, 15 tracks per day, sounding radiation is sent downwards, the backscattered signal is sampled and interpreted.

• Differences between lidars: wavelength, observation geometry and time, HSRL capability, averaging distance, vertical resolution, noise.

Future lidars

ATLID

2006 2007 2008 2009 2010 2011 2012 2013 2014 2015 2016 2017 2018 2019 2020 2021 2022 2023

Differences and similarities of space-borne lidars

Parameter	Symbol	CALIOP	ALADIN	ATLID
Altitude, [km]	Ζ	$688^{\#}$	320	393
Orbital inclination, [deg]	Ι	98.05	97.0	97.050
Equator overpass time [LST hours]		01:30/13:30	06:00/18:00	02:00/14:00
Wavelength, [nm]	λ	532/1064	355	355
Off-nadir viewing angle [deg]		3	35	2
Cross-polar radiance detection		YES	NO	YES
Pulse Repetition Frequency, [Hz]	PRF	20	50 (2) [*]	51 (25.5)*
Horizontal distance between profiles, [m]	$\Delta \mathbf{x}$	333	140 (3000)	285
Finest Vertical resolution (troposphere), [m]	Δz	30	250→1000	100
Telescope diameter, [m]	d_{tel}	1.0	1.5	0.6
Telescope Field of view, [µrad]	φ	130	19	64
Energy/pulse, [mJ]	E_{pulse}	110	100	35 (70)*
Footprint, [m]	d_{fp}	90	6	29
Laser beam divergence [µrad]	$\boldsymbol{\theta}$			45
Solar filter bandwidth, [nm]	$\Delta\lambda$	0.04/0.475	1.0/(0.067)	0.71 (0.35)**
Solar filter transmission	ξ_{filter}	0.85	0.8	0.87
Total optical system transmission	ξ_{rec}	0.67/0.68	0.6	0.62
Detector type		PMT/APD	ACCD	CCD
Detector efficiency	γ	0.11/0.4	0.8	0.79mol/0.75part

ATLID's performance, L1 and L2, low daytime noise

Lidar Curtain: ECA_EXAE_ATL_NOM_1B_20250401T063742Z_20250401T071401Z_04782A.h5



Cloud definition through scattering ratio at 532nm

$$ATB(\lambda, z) = (\beta_{mol}(\lambda, z) + \beta_{part}(\lambda, z)) \times e^{-2\int_{Z_{sat}}^{z} (\alpha_{mol}(\lambda, z') + \eta \alpha_{part}(\lambda, z')) dz'}$$

Lidar equation

$$AMB(\lambda, z) = \beta_{mol}(\lambda, z) \times e^{-2\int_{Z_{sat}}^{z} \alpha_{mol}(\lambda, z') \, dz'}$$

Attenuated molecular backscatter in the absence of particles

 $SR(\lambda, z) = \frac{ATB(\lambda, z)}{AMB(\lambda, z)}$ Scattering ratio



Compensation for wavelength difference: $\alpha_{part}(355nm)^2 = \alpha_{part}(532nm)$, $\beta_{part}(355nm)^2 = \beta_{part}(532nm)$

Past experience: making Aeolus clouds consistent with CALIPSO Feofilov et al., SAT, 2024



Past experience: Height-stratified cloud fractions for winter and summer

Feofilov et al., SAT, 2024



Converting ATLID measurements to CALIOP-like ones and estimating cloud occurrence

ATLID's L2 data converted to 532nm : ATB₅₃₂, AMBclear₅₃₂, and SR₅₃₂

Lidar Curtain: ECA_EXAE_ATL_EBD_2A_20250401T063742Z_20250402T001701Z_04782A.h5



Noise is small and is defined by the backscatter coefficient's noise

Noise-free (theoretical calculation)

SR is less noisy than APB/AMB

Feofilov et al., AMT, 2023

The first comparison - zonal mean, latitude/altitude cloud fraction



Geographical distribution of high/mid/low clouds



Future steps

Merging ATLID with CALIPSO: 2024*-2025 vs 2007-2023* Choosing the reference zones for high-level clouds (P<440hPa)

CAH - Spring (2008-2018)











Merging ATLID with CALIPSO: 2024*-2025 vs 2007-2023* Choosing the reference zones for low-level clouds (P>680hPa)

CAL - Spring (2008-2018)











Take home messages

- To detect long-term trends in cloud radiative effects and feedbacks, one needs to merge cloud records from several lidars (20+ years for 95% confidence)
- ATLID alone demonstrates excellent sensitivity to clouds and aerosols and low daytime noise, but its clouds are not directly comparable to those of CALIPSO.
- Merging method adapted from ALADIN/Aeolus vs CALIOP/CALIPSO study, which yielded -2%±5% consistency between the mean cloud fields
- The first comparisons are encouraging, but more statistics is needed (a continuous baseline starting from the beginning of the mission)
- Future plans: adding more data, adjusting the detection thresholds, adding IceSat2 lidar for cross-calibration, publishing the joint cloud dataset.